

Continued Fractions and Conformal Mappings for Domains with Angle Points

Pyotr N. Ivanshin¹

Abstract. Here we construct the conformal mappings with the help of the continued fraction approximations. We first show that the method of [19] works for conformal mappings of the unit disk onto domains with acute external angles at the boundary. We give certain illustrative examples of these constructions. Next we outline the problem with domains which boundary possesses acute internal angles. Then we construct the method of rational root approximation in the right complex half-plane. First we construct the square root approximation and consider approximative properties of the mapping sequence in Theorem 1. Then we turn to the general case, namely, the continued fraction approximation of the rational root function in the complex right half-plane. These approximations converge to the algebraic root functions $\sqrt[N]{z}$, $N \in \mathbf{N}$, $z \in \mathbf{C}$, $\operatorname{Re} z > 0$. This is proved in Theorem 2 of the article. Thus we prove convergence of this method and construct conformal approximate mappings of the unit disk onto domains with angles and thin domains. We estimate the convergence rate of the approximation sequences. Note that the closer the point is to zero or infinity and the lower is the ratio k/N the worse is the approximation. Also we give the examples that illustrate the conformal mapping construction.

Keywords--- Conformal mapping, approximation, continued fraction, complex variables, rational function.

MSC. 30C30, 30C20.

I. INTRODUCTION

This article extends and develops paper [19]. There we presented the reparametrization method of conformal mapping of the unit disk onto the given simply connected domain with a smooth boundary. This method is based on reduction of Fredholm integral equation to a sufficiently large linear equation system and on the boundary curve reparametrization. The solution possesses polynomial form that can be easily analyzed.

The method can be considered as one of the rapidly converging methods according to classification of [14]. The computation cost is actually similar to Theodorsen's method or Fornberg method [10]. Let us compare the reparametrization method of [19] with the other conformal mapping methods.

We do not consider the auxiliary mapping of the unit disk into subdomain of the given domain D as in the set of osculation methods [2]. The method of [19] does not require a sufficiently good initial approximation of the conformal mapping as the graphical methods such as that of [11]. The method does not apply any auxiliary constructions at the domain interior (domain triangulation [8], circle packing [15], domain decompositions, such as

¹ Department of Mechanics and Mathematics, Kazan Federal University. E-mail: pivanshi@yandex.ru

meshes of [24]). We do not need any iterative conformal mappings as in the zipper algorithm or the Schwartz-Christoffel mapping [7, 13]. We construct our polynomial solution differently to the Fornberg polynomial method [9] that involves consequent approximations through suitable point choice at the domain boundary. Also we do not apply the solutions of auxiliary boundary value problems (the conjugate function method, Wegmann method [22, 23]). Finally, the advantages of the method presented in [19] are the following: 1) it is devoid of auxiliary constructions, 2) it brings us to the mapping function in a polynomial form. The mapping function is a Taylor polynomial for the unit disk or a Laurent polynomial for the annulus in the case of multiconnected domains [1], [18].

Let us recall the basic construction steps of the reparametrization method [19].

Consider a finite simply connected domain D bounded by the smooth curve $L = \{z = z(t), t \in [0, 2\pi]\}$, $z(0) = z(2\pi)$. We trace the domain D counterclockwise along L as the parameter t increases. We only deal with the cases in which the boundary L representation is as follows:

$$z(t) = x(t) + iy(t) = \sum_{k=-m}^n c_k e^{ikt}. \quad (1)$$

Note that any smooth boundary may be approximated by a Fourier polynomial of this type.

If Fourier polynomial representation (1) of the curve L possesses no summands with the negative degrees of e^{it} then the function that maps the unit disk to the domain D is immediately polynomial:

$$Z(\zeta) = \sum_{k=0}^n c_k \zeta^k.$$

Assume now that representation (1) contains nonzero coefficients c_{-l} , $l \in \mathbf{N}$. Then it is possible to construct an approximate conformal mapping under reparametrization of (1) [16] leading to the coefficients c_{-l} , $l \in \mathbf{N}$, elimination.

In order to find this reparametrization $t(\theta)$, $\theta \in [0, 2\pi]$, we first construct the inverse function $\theta(t) = \arg(\zeta(z))|_{z=z(t) \in L}$. Here $\zeta(z)$ is the analytic function that gives the conformal mapping of D onto the unit disk so that $\zeta(0) = 0$. Let us denote by $q(t)$ the difference $\theta(t) - \arg z(t)$. The necessary condition for the function $\ln \frac{\zeta(z)}{z}$ to be analytic in D is just as in [16] the equation

$$q(t) = \frac{1}{\pi} \int_0^{2\pi} q(\tau) (\arg[z(\tau) - z(t)])'_\tau d\tau + \frac{1}{\pi} \int_0^{2\pi} \ln |z(\tau)| (\ln |z(\tau) - z(t)|)'_\tau d\tau. \quad (2)$$

We consider the factor $(e^{i\tau} - e^{it})$ in the expression of $z(\tau) - z(t)$ in order to separate the improper VP

integral in the last integral equation. Finally, the function $q(t)$ is the solution of the Fredholm integral equation of the second kind (2). Note that the integral kernel $\frac{1}{\pi} \frac{\partial(\arg(z(\tau) - z(t)))}{\partial \tau} = \frac{1}{\pi} \operatorname{Im} \left[\frac{\partial z'(\tau)}{z(\tau) - z(t)} \right]$ coincides with the operator $K_1(\tau, t)$ of [21]. We solve this integral equation reducing it to the finite linear equation system without converging iterations proposed in [21].

This integral equation has the set of solutions $q(t) = \alpha_0 + \sum_{p=1}^{\infty} \alpha_n \cos nt + \beta_n \sin nt$ that differ by an arbitrary summand α_0 . Equation (2) is uniquely resolvable if we set the value $\frac{1}{2\pi} \int_0^{2\pi} q(\tau) d\tau = 0$ [19], or fix the boundary image $q(t_0) = q_0$ [21]. Indeed, the number 1 is the simple eigenvalue of $K_1(\tau, t)$ with the eigenfunction $f_0 \equiv 1$ [21] and corresponds to rotation of the unit disk. So we search only for the coefficients $\alpha_n, \beta_n, n \geq 1$. The operator $K_1(\tau, t) - I$ is invertible in the subspace of $L^2[0, 2\pi]$ spanned by $\cos nt, \sin nt, n \geq 1$.

We search for the approximate function $q(t)$ in the form $q(t) = \sum_{p=1}^M \alpha_n \cos nt + \beta_n \sin nt, M \in \mathbf{N}$.

Reduce equation (2) to the uniquely resolvable finite linear system over the Fourier coefficients $\alpha_n, \beta_n, n \geq 1$, of the function $q(t)$.

$$\begin{pmatrix} AA & AB \\ BA & BB \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} F \\ G \end{pmatrix},$$

here

$$\alpha = \begin{pmatrix} \alpha_1 \\ \dots \\ \alpha_M \end{pmatrix}, \quad \beta = \begin{pmatrix} \beta_1 \\ \dots \\ \beta_M \end{pmatrix}.$$

The vectors

$$F = \begin{pmatrix} f_1 \\ \dots \\ f_M \end{pmatrix}, \quad G = \begin{pmatrix} g_1 \\ \dots \\ g_M \end{pmatrix}$$

on the right-hand side of the equation system consist of the corresponding Fourier coefficients obtained by the following technique: We separate the summand $\cot \frac{\tau - t}{2}$ in the kernel, apply Hilbert formula and find Fourier

coefficients of the integral with the remained continuous kernel as usual.

The block matrices of size M

$$AA, AB, BA, BB$$

consist of the elements

$$AA = \left(\delta_{ln} - \frac{1}{\pi^2} \int_0^{2\pi} \cos(n\tau) d\tau \int_0^{2\pi} K(\tau, t) \cos(lt) dt \right)_{l,n=1}^M,$$

$$AB = \left(-\frac{1}{\pi^2} \int_0^{2\pi} \sin(n\tau) d\tau \int_0^{2\pi} K(\tau, t) \cos(lt) dt \right)_{l,n=1}^M,$$

$$BA = \left(-\frac{1}{\pi^2} \int_0^{2\pi} \cos(n\tau) d\tau \int_0^{2\pi} K(\tau, t) \sin(lt) dt \right)_{l,n=1}^M,$$

$$BB = \left(\delta_{ln} - \frac{1}{\pi^2} \int_0^{2\pi} \sin(n\tau) d\tau \int_0^{2\pi} K(\tau, t) \sin(lt) dt \right)_{l,n=1}^M,$$

here δ_{ln} is the Kronecker delta function. Also

$$\begin{aligned} K(\tau, t) &= \text{Im} \left[\ln \frac{z(\tau) - z(t)}{e^{i\tau} - e^{it}} \right]_{\tau} = \\ &= \text{Im} \left[\ln \left(\sum_{k=1}^n c_k e^{ikt} \sum_{l=0}^{k-1} e^{il(\tau-t)} - \sum_{j=1}^m c_{-j} e^{-ij\tau} \sum_{l=0}^{j-1} e^{il(\tau-t)} \right) \right]_{\tau} \end{aligned}$$

and

$$L(\tau, t) = \text{Re} \left[\ln \frac{z(\tau) - z(t)}{e^{i\tau} - e^{it}} \right]_{\tau} =$$

$$= \operatorname{Re} \left[\ln \left(\sum_{k=1}^n c_k e^{ikt} \sum_{l=0}^{k-1} e^{il(\tau-t)} - \sum_{j=1}^m c_{-j} e^{-ij\tau} \sum_{l=0}^{j-1} e^{il(\tau-t)} \right) \right]_{\tau}$$

The cost of the linear system solution method is $O(N^2)$, where N is the degree of the Fourier polynomial approximating $q(t)$. Now $z(t) = z(t(\theta)) = Z(e^{i\theta})$, here $\theta(t) = \arg z(t) + q(t)$, and the unit disk is mapped to the domain bounded by the given smooth boundary $z(t)$ with the help of the Cauchy integral formula. So we construct an approximate polynomial conformal mapping. Similar method was also applied for construction of the annulus conformal mapping onto an arbitrary multiconnected domain with the smooth boundary in [1, 17].

Note that we can reconstruct $q'(t)$ instead of $q(t)$ in the case of smooth boundary [19]. So this method can also be considered as one of the methods using the derivatives [14].

The drawback of the reparametrization method is that it does not cover the conformal mappings of the unit disk onto domains with non-smooth boundaries. For instance, in the case of a domain with the angle ϕ for $t = t_0$ equation (2) turns into

$$\begin{aligned} \phi q(t) = & \int_0^{2\pi} q(\tau) \frac{\partial(\arg(z(\tau) - z(t)))}{\partial \tau} d\tau + \\ & + \int_0^{2\pi} \ln |z(\tau)| \frac{\partial[\ln |z(\tau) - z(t)|]}{\partial \tau} d\tau \end{aligned} \quad (3)$$

at the point t_0 . In order to overcome this difficulty we apply the additional conformal mapping which "straightens" the boundary curve at the corresponding point. Then we apply the reparametrization method to the new domain with the smooth boundary and again apply the conformal mapping that "bends" the boundary back to the initial one. Our aim is to represent this final mapping as the polynomial fraction.

In the article we apply the modification of the conformal mapping construction of [19] both for domains with boundary angles and for slender regions. We present the mapping as a polynomial fraction. We first show that the method of [19] is applicable to domains with acute external angles. Then we present the polynomial fraction construction for the internal angle equal to $\pi/2$ and conformally map the unit disk to the domain with such an angle. After that we construct the polynomial fraction for the angles $k\pi/N$, $k < N \in \mathbf{N}$. Finally we show that this approach is valid for the conformal mapping of the unit disk to the slender region.

II. METHODS

A. The case of an internal angle greater than π

The method of [19] allows us to solve the conformal mapping construction problem for any contour with the boundary curve forming internal angles greater than π . This can be illustrated by certain examples.

Let the angle point correspond to the value 0 of the parameter, the internal angle be equal to $\pi\alpha, 2 > \alpha > 1$.

Then the representation of the boundary curve equation in the neighborhood of the angle point has the form

$z(t) = (1 - e^{it})^\alpha K, K \in \mathbb{R}$. The difference between the Fourier series partial sum $S_n(x)$ and the function

$f(x)$ itself is expressed by the formula

$$S_n(x) - f(x) = \frac{1}{\pi} \int_0^\varepsilon \frac{1}{2} (f(x+t) + f(x-t) - 2f(x)) \frac{\sin(nt)}{t} dt + o(1) \quad ([25], \text{Chapter 2, formula (7.1)}).$$

this case, $S_n(0) - z(0) = K \frac{F(n, \varepsilon, \alpha)}{\pi} + o(1)$, where

$$F(n, \varepsilon, \alpha) = 2^{\alpha+1} \int_0^\varepsilon \sin^\alpha\left(\frac{t}{2}\right) \cos\left(\frac{\alpha}{2}(t - \pi)\right) \frac{\sin(nt)}{t} dt. \quad (4)$$

For $\varepsilon \leq \frac{\pi}{2n}$ we obtain

$$F(n, \varepsilon, \alpha) = 2^{\alpha+1} \int_0^\varepsilon \sin^\alpha\left(\frac{t}{2}\right) \cos\left(\frac{\alpha}{2}(t - \pi)\right) \frac{\sin(nt)}{t} dt \leq$$

$$\leq 2 \int_0^\varepsilon t^\alpha \frac{\sin(nt)}{t} dt \leq 2 \int_0^\varepsilon nt^\alpha dt =$$

$$= 2 \frac{n\varepsilon^{\alpha+1}}{\alpha+1} \leq \frac{\pi^{\alpha+1}}{2^\alpha n^\alpha (\alpha+1)} \leq \frac{\pi}{2} \left(\frac{\pi}{2n}\right)^\alpha \leq \frac{\pi^2}{4n}.$$

Hence for all $\alpha > 1$ the difference between the values of the Fourier series partial sum $S_n(x)$ and the function $z(t)$ itself can be made arbitrarily small for a sufficiently large n . That is, we have the convergence of the Fourier series at the angle point, regardless of the angle. This allows us to apply the conformal mapping construction method of [19].

Example 1. Consider the piecewise circular contour (two semicircles and one circle quarter) with the external angle $\pi/2$ (Fig.1). First we approximate the boundary with a Fourier polynomial of degree 10. Then we construct the approximating polynomial of degree 50.

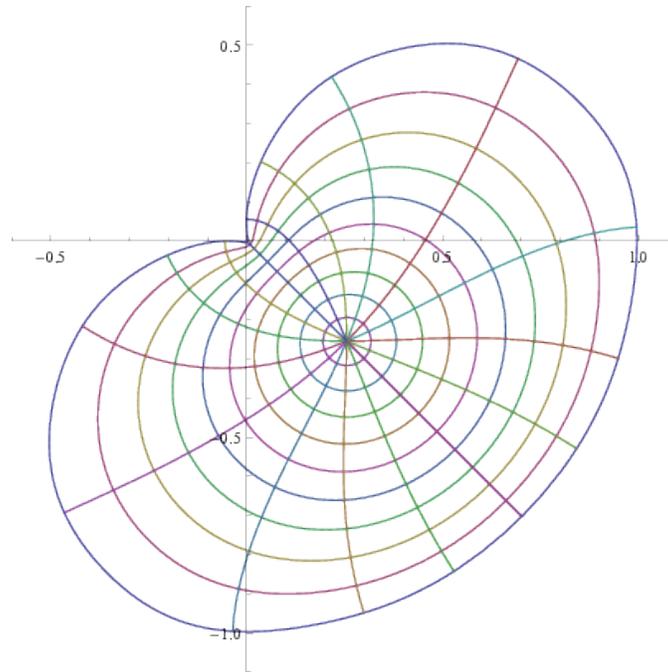


Figure 1: The approximation of the contour with the external angle $\pi/2$ and the polar net image.

Example 2. The three-semicircle contour with the external angle 0 (Fig.2). Again we first approximate the boundary with a Fourier polynomial of degree 10. We then construct the approximating polynomial of degree 50.

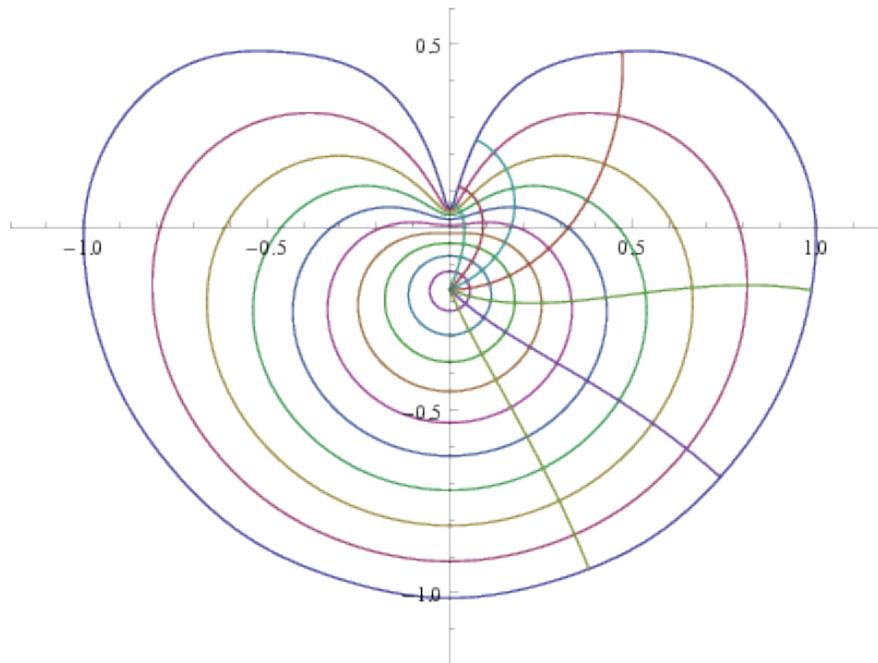


Figure 2: The approximation of the contour with the external angle 0 and a part of the polar net image

The similar example for the doubly connected domain with rectangular inner boundary can be found in [17].

B. The construction scheme for the case of an internal angle less than π

It is computationally difficult to apply the conformal mapping construction of [19] for a domain whose boundary forms an acute internal angle. Then the mapping polynomial converges slowly and the resulting conformal mapping angle point does not look like an angle at all (sort of a bubble).

Consider a curve whose behavior at an angle point is similar to $(1 - e^{it})^\alpha K$, $K \in \mathbf{R}$, with $\alpha \in (0,1)$ in a neighborhood of $t = 0$. Then again by Dini criterion ([25], Chapter 2, Section 6) we have a singularity of type $t^{\alpha-1}$ at $t = 0$ and the Fourier series slowly converges at $t = 0$. In order to estimate $F(n, \varepsilon, \alpha)$, defined by

relation (4), we consider the following inequalities: $\sin^\alpha(t/2) \geq (\frac{t}{\pi})^\alpha$, $\frac{\sin(nt)}{t} \geq \frac{2n}{\pi}$,

$\cos(\frac{\alpha}{2}(t - \pi)) \geq \cos(\frac{\alpha}{2})$. Then we have $F(n, \frac{\pi}{2n}, \alpha) \geq \cos(\frac{\alpha\pi}{2}) \frac{2}{n^\alpha(\alpha+1)}$ for $\varepsilon = \frac{\pi}{2n}$. Hence

$F(n, \frac{\pi}{2n}, \frac{1}{\ln n}) \rightarrow \frac{2}{e}$ as $n \rightarrow \infty$. So, for the singular point $t = 0$, the Fourier series rate of convergence to the

generating function $z(t)$ is the less the closer α is to 0. Thus, the method from [19] is difficult to apply, since even the Fourier series poorly approximate a curve with such an angle point.

Let the domain boundary be angled and the angle be equal to $k\pi/N$, $N = 2,3,\dots$, $k \in \{1,2,\dots,N-1\}$.

The main idea of the mapping construction is to first put the angle point at 0, make the domain smooth with the mapping $z^{N/k}$, construct the conformal mapping onto this smooth domain and then apply the fraction polynomial approximation of the inverse mapping $\sqrt[N]{z^k}$. Note that the domain should completely lie in the right half-plane. In the other case we should apply fraction linear mapping in order to put the domain into the angle.

The continued fraction converges to \sqrt{x} at $x = 0$ faster than the Taylor expansion of the function $\sqrt{\frac{x-a}{a} + 1}$ into degrees of $(x-a)$ to the function $\sqrt{\frac{x-a}{a} + 1}$ itself at $x = 0$ [5]. The most thorough and refined method

here is the Padé rational function approximation of the algebraic function [3, 4]. Note that these approximations are optimal in the set of fraction polynomials though their construction requires application of Euclidean algorithm and additional investigation of the holomorphy domain D .

The main result here is that the recursively constructed relations converge to the continued fraction approximating any rational root $\sqrt[N]{z}$, $N \in \mathbf{N}$. The constructed sequence is clearly not Padé one. But the construction itself is fairly simple, does not possess nonunique solutions and provides convergence to the root

function at the complex right half-plane. Similar results can be found in [5]. Also the author is sure that this result can be proved along the lines of [12]. Again the proof should apply induction and we need to consider the roots of the polynomials instead of the mapping itself. Note also that the fractional polynomial mappings can be applied, for instance, to exact solution of the elasticity theory problems [20].

III. RESULTS AND DISCUSSION

A. The square root approximation

First consider the basic problem of the square root fraction polynomial representation. It is well-known that

$\sqrt{z} = 1 + \frac{z-1}{\sqrt{z}+1}$. This gives rise to the following recursive procedure:

Lemma 1 Assume that $f_n(z) = 1 + \frac{z-1}{1+f_{n-1}(z)}$, $f_1(z) = 1 + \frac{z-1}{1+z}$. Then the following facts hold true for z

with $\text{Re}[z] > 0$:

1. $\text{Re}[f_n(z)] > 0$
2. $\text{Im}[f_n(z)]$ has the same sign as $\text{Im}[z]$.
3. The fraction $\frac{\text{Im}[f_n(z)]}{\text{Re}[f_n(z)]}$ has the same sign as the fraction $\frac{\text{Im}[z]}{\text{Re}[z]}$ and $|\frac{\text{Im}[f_n(z)]}{\text{Re}[f_n(z)]}| < |\frac{\text{Im}[z]}{\text{Re}[z]}|$.

Proof. The proof is by induction on n .

The induction base is $f_1(z) = 1 + \frac{z-1}{1+z}$.

1. $\text{Re}[f_1(z)] = \frac{2|z|^2 + 2\text{Re}[z]}{|z+1|^2} > 0$.
2. $\text{Im}[f_1(z)] = \frac{2\text{Im}[z]}{|z+1|^2}$ is of the same sign as $\text{Im}[z]$.
3. Assume that $\text{Im}[z] > 0$, then $\frac{\text{Im}[f_n(z)]}{\text{Re}[f_n(z)]} = \frac{2\text{Im}[z]}{2\text{Re}[z] + 2|z|^2} < \frac{\text{Im}[z]}{\text{Re}[z]}$.

The induction step then is as follows:

1. The nominator similar to that of the induction base is $\text{Re}[z] + \text{Re}[z]\text{Re}[f_{n-1}(z)] + \text{Im}[z]\text{Im}[f_{n-1}(z)] + \text{Re}[f_{n-1}(z)] + |f_{n-1}(z)|^2 > 0$ by conjecture.

2. Similarly the sign of $\text{Im}[f_n(z)]$ coincides with the sign of $\text{Im}[f_{n-1}(z)] + \text{Im}[z]$

+ $\text{Im}[z]\text{Re}[f_{n-1}(z)] - \text{Re}[z]\text{Im}[f_{n-1}(z)]$. The last two summands are of the same sign as $\text{Im}[z]$ by conjecture.

3. Consider $\frac{\text{Im}[f_{n-1}(z)] + \text{Im}[z] + \text{Im}[z]\text{Re}[f_{n-1}(z)] - \text{Re}[z]\text{Im}[f_{n-1}(z)]}{\text{Re}[f_{n-1}(z)] + \text{Re}[z] + \text{Re}[z]\text{Re}[f_{n-1}(z)] + \text{Im}[z]\text{Im}[f_{n-1}(z)] + |f_{n-1}(z)|^2}$. Note that the respective summands of the nominator and denominator meet the desired relation so the fraction itself is less in modulus than $\frac{\text{Im}[z]}{\text{Re}[z]}$.

Statement 1 *There are no points at the right complex half-plane at which the derivative of $f_n(z)$ vanishes.*

Proof. 1. Consider z so that $\text{Im}[z] \neq 0$. Then by item 3 of Lemma 1 we have $\frac{\partial f_n(z)}{\partial \arg(z)} \neq 0$. Indeed for $n = 1$, locally $\arg(f_1(z)) = \arg(z) - \arg(z+1) = k_1 \arg(z)$, $0 < k_1 < 1$ by item 3 of Lemma 1. Let $\text{Im}[z] > 0$. Then $\forall n$ and $\arg(f_n(z)) = \arg(f_{n-1}(z) + z) - \arg(f_{n-1}(z) + 1)$ we have $k_{n-1} \arg(z) < \arg(f_{n-1}(z) + z) < \arg(z)$ and $\arg(f_{n-1}(z) + 1) = \tilde{k}_{n-1} \arg(z) < k_{n-1} \arg(z)$. So $0 < (k_{n-1} - \tilde{k}_{n-1}) \arg(z) < \arg(f_n(z)) < (1 - \tilde{k}_{n-1}) \arg(z)$.

2. Consider $z = x \in \mathbb{R}^+$. Then we must prove that $f_{n-1}'(x) + 1 + f_{n-1}(x) - xf_{n-1}'(x) > 0$ or more precisely, that $f_{n-1}(x) - xf_{n-1}'(x) > 0$. The proof is by induction. Base $f_1'(x) = \frac{2}{(x+1)^2}$. The induction step is as follows:

$$f_n(x) - xf_n'(x) = \frac{f_{n-1}(x) + x}{1 + f_{n-1}(x)} - x \frac{f_{n-1}'(x) + 1 + f_{n-1}(x) - xf_{n-1}'(x)}{(1 + f_{n-1}(x))^2} = \frac{f_{n-1}(x) + f_{n-1}^2(x) - xf_{n-1}'(x)(1-x)}{1 + f_{n-1}(x)} > 0$$

by the induction assumption and item 1 of Lemma 1.

Also since $\text{Re}[1 + f_{n-1}(z)] > 0$ for z from the right half plane the function $f_n(z)$ does not have poles in this set.

Theorem 1 *The functions $f_n(z) = 1 + \frac{z-1}{1+f_{n-1}(z)}$ converge to \sqrt{z} with the convergence rate $(\frac{1-\sqrt{z}}{1+\sqrt{z}})^n$ for*

$z, \text{Re}[z] > 0$.

Proof. First note that $|\frac{1-\sqrt{z}}{1+\sqrt{z}}| < 1$ for $z, \operatorname{Re}[z] > 0$.

Consider $\varepsilon = z - \sqrt{z}$. Then $f_1(z) = \sqrt{z} + \frac{\varepsilon(1-\sqrt{z})}{1+\sqrt{z}+\varepsilon}$,

$$f_2(z) = \sqrt{z} + \frac{\varepsilon(1-\sqrt{z})^2}{(1+\sqrt{z})^2 + \varepsilon((1+\sqrt{z}) + (1-\sqrt{z}))}, \quad \dots, \quad f_n(z) = \sqrt{z} + \frac{\varepsilon(1-\sqrt{z})^n}{(1+\sqrt{z})^n + \varepsilon K_n}, \quad \text{here}$$

$$K_n = (1+\sqrt{z})^{n-1} + K_{n-1}(1-\sqrt{z}), \quad K_1 = 1.$$

Hence

$$K_n = (1+\sqrt{z})^{n-1} \left(1 + \left(\frac{1-\sqrt{z}}{1+\sqrt{z}}\right) \frac{K_{n-1}}{(1+\sqrt{z})^{n-2}}\right) = \dots = (1+\sqrt{z})^{n-1} \left(1 + \frac{1-\sqrt{z}}{1+\sqrt{z}} + \dots + \left(\frac{1-\sqrt{z}}{1+\sqrt{z}}\right)^{n-1}\right). \quad \text{Thus}$$

$$\lim_{n \rightarrow \infty} \frac{K_n}{(1+\sqrt{z})^{n-1}} = \frac{1}{1 - \frac{1-\sqrt{z}}{1+\sqrt{z}}} = \frac{1+\sqrt{z}}{2\sqrt{z}}.$$

So,

$$\lim_{n \rightarrow \infty} \frac{\varepsilon(1-\sqrt{z})^n}{(1+\sqrt{z})^n + \varepsilon K_n} = \lim_{n \rightarrow \infty} \frac{\varepsilon(1-\sqrt{z})^n}{(1+\sqrt{z})^n \left(1 + \varepsilon \frac{K_n}{(1+\sqrt{z})^n}\right)} =$$

$$= \varepsilon \lim_{n \rightarrow \infty} \frac{(1-\sqrt{z})^n}{(1+\sqrt{z})^n \left(1 + \frac{\varepsilon}{1+\sqrt{z}} \frac{K_n}{(1+\sqrt{z})^{n-1}}\right)} = (z - \sqrt{z}) \lim_{n \rightarrow \infty} \frac{(1-\sqrt{z})^n}{(1+\sqrt{z})^n \left(1 + \frac{\sqrt{z}-1}{2}\right)} =$$

$$= \frac{z - \sqrt{z}}{1 + \frac{\sqrt{z}-1}{2}} \lim_{n \rightarrow \infty} \frac{(1-\sqrt{z})^n}{(1+\sqrt{z})^n} = 0.$$

This completes the proof.

Assume now that we have a convex domain with acute internal angles and we need to construct the conformal mapping of the unit disk onto this domain. The main construction steps are as follows: we make the domain as round as possible with square mappings. If the resulting domain does not overlap itself then we construct the approximating polynomial according to the method of [19]. Finally we construct the square root approximations of the resulting image inverse to the squares of the first step.

Example 3. Let us construct an approximate conformal map of the unit disk onto the contour with the internal angle $\pi/2$. Here we have the 11th iteration of the square root approximation and degree 50 polynomial for the initial domain (Fig.3).

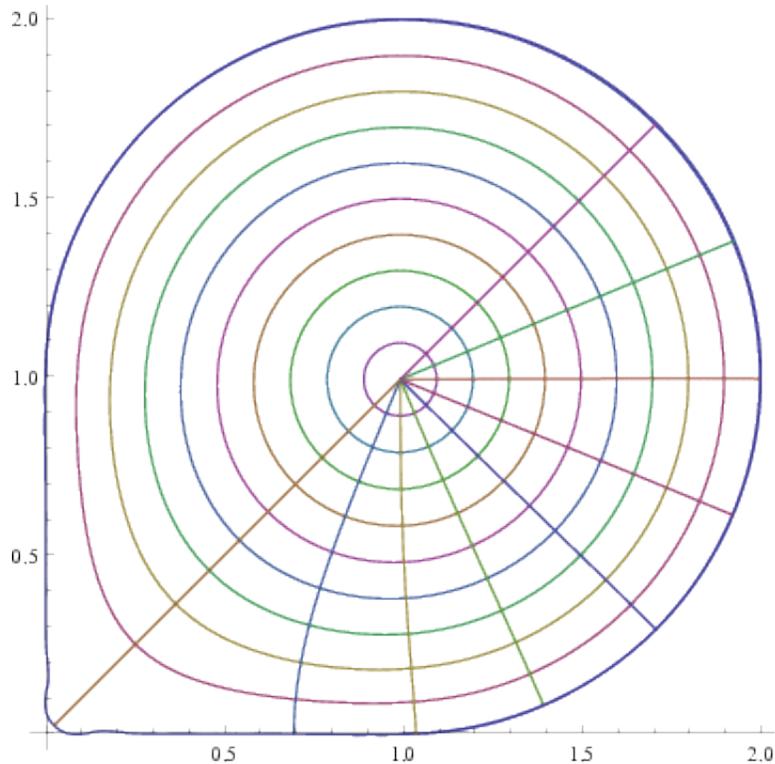


Figure 3: Contour with the internal angle equal to $\pi/2$

B. The case of $z^{\frac{k}{N}}$

Consider a natural number $N \in \mathbb{N}$. The recursive representation of the N -th root then takes the following form:

$$z^{\frac{1}{N}} = 1 + \frac{z-1}{z^{\frac{N-1}{N}} + \dots + z^{\frac{2}{N}} + z^{\frac{1}{N}} + 1} =$$

$$= 1 + \frac{z-1}{\frac{z}{z^{\frac{1}{N}}} + \frac{z}{z^{\frac{2}{N}}} + \dots + z^{\frac{2}{N}} + z^{\frac{1}{N}} + 1}$$

Also at the same time we have

$$z^{\frac{k}{N}} = z^{\frac{k-1}{N}} + \frac{z - z^{\frac{k-1}{N}}}{z^{\frac{N-k}{N}} + \dots + z^{\frac{2}{N}} + z^{\frac{1}{N}} + 1}$$

Then we express the right-hand side of the first relation only through $z^{\frac{1}{N}}$. Certain statements similar to that of Section 4 hold and we have the convergence of these fractions to the relative function degrees at the complex right half-plane. The only principally new appearance here is simultaneous proof of the result for all the representations of $z^{\frac{k}{N}}$, $k = 1, 2, \dots, N - 1$. Here we need the additional induction step for the recursive representations of $z^{\frac{k}{N}}$ and $z^{\frac{z}{kN}}$, $k = 1, 2, \dots, [N/2]$. Again the most important part is the first construction step. Assume then that for any

$k \in \{1, 2, \dots, [N/2]\}$ the first approximation of $z^{\frac{k}{N}}$ equals $1 + \frac{z-1}{z+1}$.

Theorem 2 For any z , $\text{Re}[z] > 0$, $N = 2, 3, \dots$, and $k \in \{1, \dots, N - 1\}$ the sequence of fraction-polynomial approximations converges to $z^{\frac{k}{N}}$ with the convergence rate

$$\left| z^{(k-1)/N} \left(\frac{z - N(z^{1/N} - 1)z^{\frac{[N/2]}{N}} - 1}{z - 1} \right)^n \right|.$$

Proof. Let the first approximation of $z^{1/N}$ equal $z^{1/N} + \varepsilon$. Then the first approximation of $z^{k/N}$ equals $z^{k/N} + kz^{1/N}\varepsilon + o(\varepsilon)$ and that of $z^{\frac{N-k}{N}}$ is $z^{\frac{N-k}{N}} - k\varepsilon z^{\frac{N-k-1}{N}} + o(\varepsilon)$, $k = 1, \dots, [N/2]$. We have the next approximation of $z^{1/N}$ equal to

$$\begin{aligned} f_2(z) &= 1 + (z-1) / [1 + z^{1/N} + \dots + z^{\frac{N-1}{N}} + \\ &+ \varepsilon(1 + 2z^{1/N} + \dots + [N/2]z^{\frac{[N/2]-1}{N}} - ([N/2]-1)z^{\frac{[N/2]}{N}} - \dots - z^{\frac{N-2}{N}})] = \\ &= z^{1/N} + \{ \varepsilon(1 + 2z^{1/N} + \dots + [N/2]z^{\frac{[N/2]-1}{N}} - \\ &- ([N/2]-1)z^{\frac{[N/2]}{N}} - \dots - z^{\frac{N-2}{N}})(1 - z^{1/N}) \} / \{ 1 + z^{1/N} + \dots + z^{\frac{N-1}{N}} + \\ &+ \varepsilon(1 + 2z^{1/N} + \dots + [N/2]z^{\frac{[N/2]-1}{N}} - ([N/2]-1)z^{\frac{[N/2]}{N}} - \dots - z^{\frac{N-2}{N}}) \} = \end{aligned}$$

$$= z^{1/N} + \varepsilon \{ z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+1}{N}} - (N-1)z^{\frac{[N/2]}{N}} + z^{\frac{[N/2]-1}{N}} + \dots + 1 \} / \{ 1 + z^{1/N} + \dots + z^{\frac{N-1}{N}} + \varepsilon(1 + 2z^{1/N} + \dots + [N/2]z^{\frac{[N/2]-1}{N}} - ([N/2]-1)z^{\frac{[N/2]}{N}} - \dots - z^{\frac{N-2}{N}}) \}.$$

The third approximation then equals

$$f_3(z) = z^{1/N} + \varepsilon(z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+1}{N}} - (N-1)z^{\frac{[N/2]}{N}} + z^{\frac{[N/2]-1}{N}} + \dots + 1)^2 / [(1 + z^{1/N} + \dots + z^{\frac{N-1}{N}})^2 + \varepsilon(1 + 2z^{1/N} + \dots + [N/2]z^{\frac{[N/2]-1}{N}} - ([N/2]-1)z^{\frac{[N/2]}{N}} - \dots - z^{\frac{N-2}{N}})((1 + z^{1/N} + \dots + z^{\frac{N-1}{N}}) + (z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+2}{N}} - (N-1)z^{\frac{[N/2]+1}{N}} + z^{\frac{[N/2]}{N}} + \dots + 1))].$$

Again as in the square root case we have

$$f_n(z) = z^{1/N} + \varepsilon \frac{(z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+1}{N}} - (N-1)z^{\frac{[N/2]}{N}} + z^{\frac{[N/2]-1}{N}} + \dots + 1)^n}{(1 + z^{1/N} + \dots + z^{\frac{N-1}{N}})^n + \varepsilon K_n}.$$

Here $K_n = K_{n-1}((1 + z^{1/N} + \dots + z^{\frac{N-1}{N}}) + (z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+1}{N}} - (N-1)z^{\frac{[N/2]}{N}} + z^{\frac{[N/2]-1}{N}} + \dots + 1))$.

Since $|\frac{K_n}{(1 + z^{1/N} + \dots + z^{\frac{N-1}{N}})^n}|$ is bounded by

$$|1 + \frac{z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+1}{N}} - (N-1)z^{\frac{[N/2]}{N}} + z^{\frac{[N/2]-1}{N}} + \dots + 1}{1 + z^{1/N} + \dots + z^{\frac{N-1}{N}}}|$$

and

$$|\frac{z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+1}{N}} - (N-1)z^{\frac{[N/2]}{N}} + z^{\frac{[N/2]-1}{N}} + \dots + 1}{1 + z^{1/N} + \dots + z^{\frac{N-1}{N}}}| < 1$$

we have the convergent sequence for any z , $\text{Re}[z] > 0$.

Lemma 2 For z such that $\text{Re}[z] > 0$ and any $N = 2, 3, \dots$, we have

$$|\frac{z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+1}{N}} - (N-1)z^{\frac{[N/2]}{N}} + z^{\frac{[N/2]-1}{N}} + \dots + 1}{1 + z^{1/N} + \dots + z^{\frac{N-1}{N}}}| < 1.$$

Proof. In order to prove the relation consider z such that $\operatorname{Re}[z] > 0$, $\operatorname{Im}[z] \geq 0$. Consider $t = z^{1/N} = r^{1/N} e^{i\phi}$, $\phi \in (-\frac{\pi}{2N}, \frac{\pi}{2N})$. The maximal value of the fraction happens for $\phi = \pm \frac{\pi}{2N}$ as a boundary value of an analytic function on t . Indeed then we have the function $\frac{t^{N-1} + \dots + t^{[N/2]+1} - (N-1)t^{[N/2]} + t^{[N/2]-1} + \dots + 1}{1+t+\dots+t^{N-1}}$ that does not possess poles in the right half-plane since the denominator real part is strictly positive for t such that $\operatorname{Re}[t] > 0$, $|\arg[t]| < \frac{\pi}{2N}$.

Assume first that N is even. Consider the real part of the nominator

$$\begin{aligned} & r^{\frac{N-1}{N}} \cos\left(\frac{(N-1)\pi}{2N}\right) + \dots + r^{\frac{1}{N}} \cos\left(\frac{\pi}{2N}\right) + 1 - Nr^{1/2} \cos(\pi/4) = \\ & = r^{\frac{N-1}{N}} \sin\left(\frac{\pi}{2N}\right) + \dots + r^{\frac{1}{2} - \frac{1}{N}} \sin\left(\frac{(N-2)\pi}{2N}\right) + r^{1/2} \cos(\pi/4) + \\ & + r^{\frac{1}{2} + \frac{1}{N}} \cos\left(\frac{(N-2)\pi}{2N}\right) + \dots + r^{\frac{1}{N}} \cos\left(\frac{\pi}{2N}\right) + 1 - Nr^{1/2} \cos(\pi/4). \end{aligned}$$

Similarly for the imaginary part we have

$$\begin{aligned} & r^{\frac{N-1}{N}} \cos\left(\frac{\pi}{2N}\right) + \dots + r^{\frac{1}{2} - \frac{1}{N}} \cos\left(\frac{(N-2)\pi}{2N}\right) + r^{1/2} \sin(\pi/4) + \\ & + r^{\frac{1}{2} + \frac{1}{N}} \sin\left(\frac{(N-2)\pi}{2N}\right) + \dots + r^{\frac{1}{N}} \sin\left(\frac{\pi}{2N}\right) - Nr^{1/2} \sin(\pi/4). \end{aligned}$$

In order to compare the absolute values of the nominator and denominator we project their components onto the same line $\phi = \pi/4$ since the absolute value of the negative deformation $-Nr^{1/2}(\cos(\pi/4) + \sin(\pi/4))$ is maximal in this direction. For any $k = 1, \dots, N-1$, the absolute value of $z^{\frac{k}{N}}$ projection onto this line is $\sqrt{2}$ times less than the number $z^{\frac{k}{N}}$ real and imaginary part sum.

Then for any $k = 1, \dots, [N/2]-1$, we have

$$\begin{aligned}
 & r^{1-\frac{k}{N}} \sin\left(\frac{k\pi}{2N}\right) + r^{\frac{k}{N}} \cos\left(\frac{k\pi}{2N}\right) + r^{1-\frac{k}{N}} \cos\left(\frac{k\pi}{2N}\right) + r^{\frac{k}{N}} \sin\left(\frac{k\pi}{2N}\right) - \sqrt{2}r^{1/2} = \\
 & = r^{1/2} \left(r^{1/2-\frac{k}{N}} \sin\left(\frac{k\pi}{2N}\right) + r^{\frac{k}{N}-1/2} \cos\left(\frac{k\pi}{2N}\right) + r^{1/2-\frac{k}{N}} \cos\left(\frac{k\pi}{2N}\right) + r^{\frac{k}{N}-1/2} \sin\left(\frac{k\pi}{2N}\right) - \sqrt{2} \right) \geq \\
 & \geq r^{1/2} \left(r^{\frac{k}{N}-1/2} \cos\left(\frac{k\pi}{2N}\right) + r^{1/2-\frac{k}{N}} \cos\left(\frac{k\pi}{2N}\right) - \sqrt{2} \right) \geq \\
 & \geq r^{1/2} \sqrt{2} \left(r^{\frac{k}{N}-1/2} + r^{1/2-\frac{k}{N}} - 2 \right) \geq 0.
 \end{aligned}$$

The equality happens only for $z = 0$.

Let N be an odd number. Then similarly to the even case we project our sums onto the line $\phi = \frac{[N/2]\pi}{2N}$ and gather $z^{\frac{k}{N}}$ and $z^{\frac{N-1-k}{N}}$, $k = 0, \dots, [N/2]$. The projection absolute value for any $k = 0, \dots, N-1$, equals $\operatorname{Re}[z^{\frac{k}{N}}] \cos\left(\frac{[N/2]\pi}{2N}\right) + \operatorname{Im}[z^{\frac{k}{N}}] \sin\left(\frac{[N/2]\pi}{2N}\right)$.

The relation we need then equals

$$\begin{aligned}
 & \left(r^{1-\frac{k+1}{N}} \cos\left(\frac{(N-k-1)\pi}{2N}\right) + r^{\frac{k}{N}} \cos\left(\frac{k\pi}{2N}\right) \right) \cos\left(\frac{[N/2]\pi}{2N}\right) + \\
 & + \left(r^{1-\frac{k+1}{N}} \sin\left(\frac{(N-k-1)\pi}{2N}\right) + r^{\frac{k}{N}} \sin\left(\frac{k\pi}{2N}\right) \right) \sin\left(\frac{[N/2]\pi}{2N}\right) - \\
 & - r^{\frac{[N/2]}{N}} \left(\cos^2\left(\frac{[N/2]\pi}{2N}\right) + \sin^2\left(\frac{[N/2]\pi}{2N}\right) \right) = \\
 & = r^{1-\frac{k+1}{N}} \cos\left(\frac{([N/2]-k)\pi}{2N}\right) + r^{\frac{k}{N}} \cos\left(\frac{(k-[N/2])\pi}{2N}\right) - r^{\frac{[N/2]}{N}} \geq
 \end{aligned}$$

$$\geq r^{\frac{[N/2]}{N}} \left(r^{\frac{N-1-k}{2N}} + r^{\frac{k-N-1}{2N}} \right) \frac{1}{\sqrt{2}} - 1 \geq 0.$$

The lemma is proved.

The convergence rate for $z^{k/N}$ can be estimated by some multiple of

$$\begin{aligned} & \left| z^{(k-1)/N} \left(\frac{z^{\frac{N-1}{N}} + \dots + z^{\frac{[N/2]+1}{N}} - (N-1)z^{\frac{[N/2]}{N}} + z^{\frac{[N/2]-1}{N}} + \dots + 1}{1 + z^{1/N} + \dots + z^{\frac{N-1}{N}}} \right)^n \right| = \\ & = \left| z^{(k-1)/N} \left(\frac{z - N(z^{1/N} - 1)z^{\frac{[N/2]}{N}} - 1}{z - 1} \right)^n \right|. \end{aligned}$$

So the more acute the angle and the closer z is to 0 the worse is the approximation convergence.

This completes the proof of the theorem.

We now construct the following mappings exactly as in Example 3.

Example 4. The contour (two lines and the circular sector) with the angle $\pi/3$. We first approximate the unfolded domain by the method of [19] and then fold the result with the fractional polynomial mapping. We apply the recursive formula

$$g_n(z) = 1 + \frac{z-1}{\frac{z}{g_{n-1}(z)} + g_{n-1}(z) + 1}, \quad g_1(z) = 1 + \frac{z-1}{z+1}.$$

The unfolded domain was approximated by the polynomial of degree 50. We next apply the 6th fraction iteration to fold the domain back to the angled one (Fig.4).

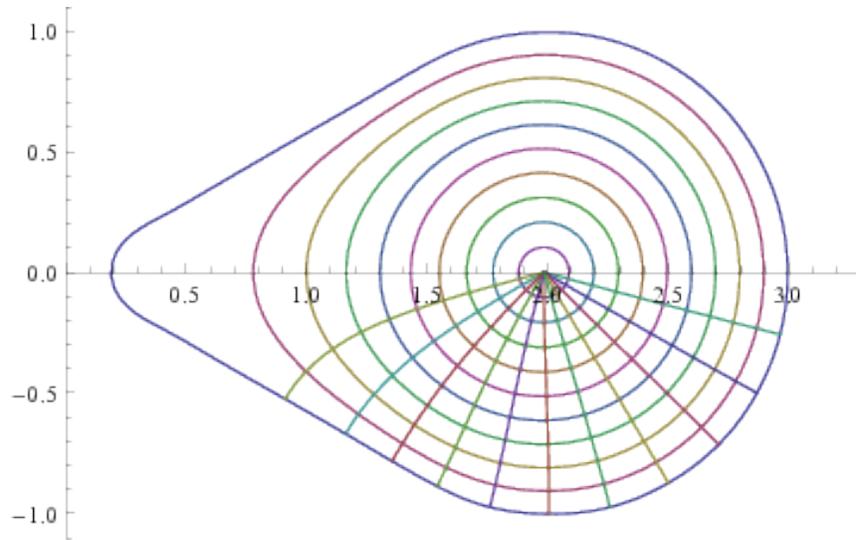


Figure 4: Sixth approximation of the contour with the internal angle equal to $\pi/3$ and a part of the polar net image

Example 5. Similar contour (two lines and the circular sector) with the angle $2\pi/3$. We again approximate the unfolded domain by the method of [19] and then fold the result with the fractional polynomial mapping. Here the main formula is simply

$$h_n(z) = \frac{z}{g_n(z)}$$

for $g_n(z)$ of Example 4. The unfolded domain was approximated by the polynomial of degree 50. We next apply the 4th fraction iteration to fold the domain back to the angled one (Fig.5).

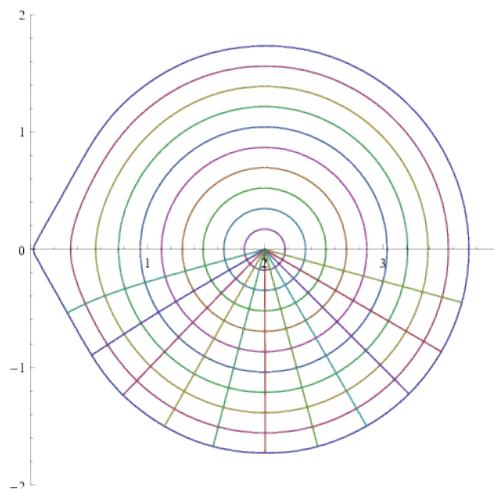


Figure 5: Fourth approximation of the contour with the internal angle equal to $2\pi/3$ and a part of the polar net image

These examples show us that the more acute is the internal angle the harder it is to approximate it.

C. The case of thin domains

Consider the case of slender regions. The second problem for us is the case of relatively thin domains (e.g. ellipse with two significantly different axes). Consider the integral equation of [19] kernel behavior for τ close to the point t of the largest possible curvature $\kappa(t) : \frac{d}{d\tau} \arctg\left(\frac{y(\tau) - y(t)}{x(\tau) - x(t)}\right) = \kappa(t) |z(t)'| / 2 + o(1)$. Then the diagonal elements of the relative linear equation system matrix are close to $\kappa(t)$ and are also large. Thus, the greater the curvature $\kappa(t)$ of the curve in t , the worse the convergence of the polynomial solution.

The authors of [6] numerically solve the singular integral equation in order to find the conformal mappings from elliptic to slender regions. The method of recursive fractions is also applicable to the conformal mapping construction of a disk onto a thin domain. The main problem here is the so-called point crowding phenomenon. Here we achieve the similar results (domain sides ratio $1/4$) with our method as a natural application. We first make the domain less slender with the help of the square mapping $(z - a)^2$, here the point a lies outside the domain and close to its boundary point of maximal curvature. We cannot take this point at the boundary itself since then we achieve the domain that cannot be immediately inserted into the right half-plane at the neighbourhood of a . Secondly we apply the approximate conformal mapping construction algorithm. Finally we apply the square root approximation in order to return to the domain with the given boundary.

Now, if a domain lies between two sides of the right angle closely to the vertex then we consider the mapping of the disk onto the squared domain and the square root approximation of the angle.

Example 6. Consider the ellipse of semiaxes 1 and $1/4$: $x^2 + 16y^2 = 1$. Let us construct an approximate conformal mapping of the unit disk onto this ellipse.

The initial method of [19] provides us with the following result for the polynomial of degree 1200 (Fig.6).

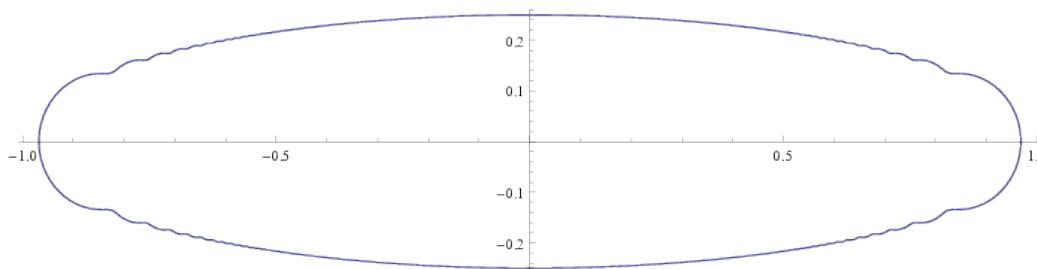


Figure 6: The ellipse polynomial approximation

Here we consider the 20th square root iterations and 1000 degree polynomial (Fig.7). Similar picture under only polynomial approximation due to the point crowding phenomenon happens for polynomial of degree 10^4 .

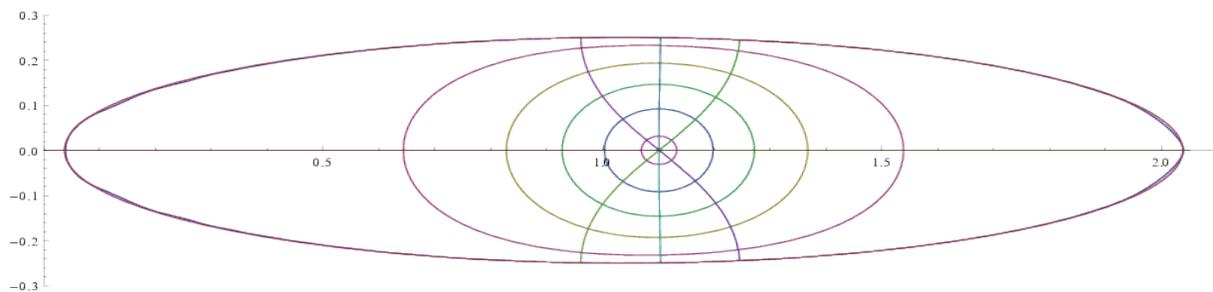


Figure 7: The ellipse fraction polynomial approximation

IV. SUMMARY

We first showed that the method of [19] works for conformal mappings of the unit disk onto domains with acute external angles at the boundary. Next we outlined the problem with domains which boundary possesses acute internal angles. Then we constructed a method of rational root approximation in the right complex half-plane. Also we proved convergence of this method and constructed conformal approximate mappings of the unit disk onto domains with angles and thin domains. All the constructions of the article are supported by examples.

V. CONCLUSION

Our approach of continuous fractions application to conformal mapping constructions shows good convergence and may be applied, for example to certain problems of mathematical physics, particularly, to elasticity theory problems.

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